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Corrections, 15 June 2001

**Title:**

Space-efficient vectors and deques

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5th Workshop on Algorithm Engineering  
(to appear)

# Background: the Copenhagen STL

**Project start:** September 2000

**Goal:** alternative/enhanced versions of individual STL components

**Contributors:** ca. 20 students have written parts of the library

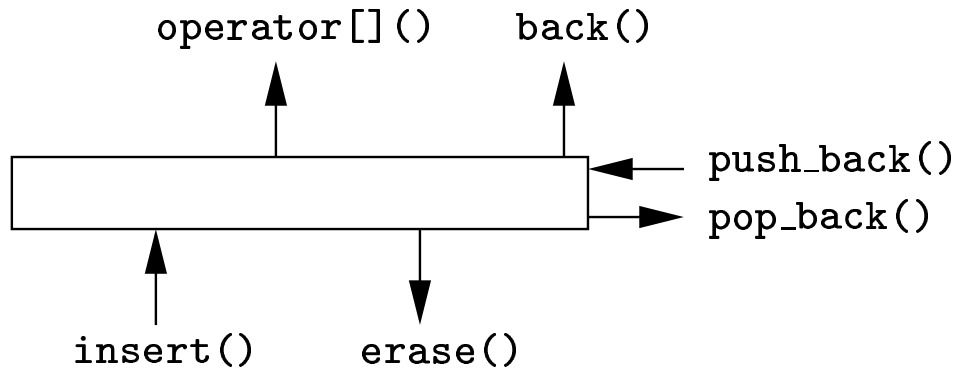
**Status:** first implementations for the most interesting modules exist

**Emphasis:** performance engineering, software engineering, algorithmics

**Availability:** <http://cphstl.dk>

**Current problem:** How to transfer the existing prototypes to a product?

## std::vector in the C++ library



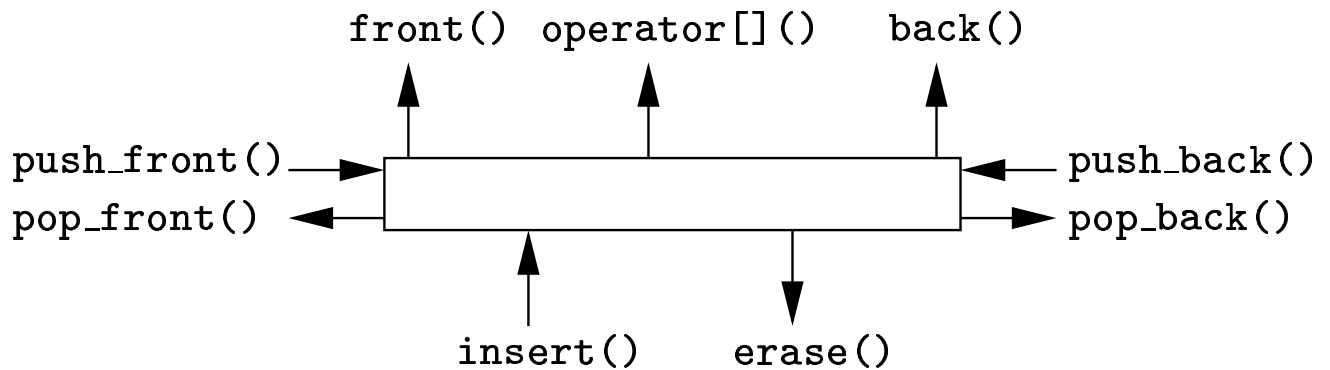
### Required by the C++ standard

- sequence operations in  $O(1)$  amortized time
- modifying operations in linear time
- according to a technical correction elements must be stored contiguously

### SGI STL implementation

- standard doubling technique
- unbounded extra space
- $n$  push\_backs require  $\Theta(n)$  element moves

## std::deque in the C++ library



### Required by the C++ standard

- sequence operations in  $O(1)$  worst-case time
- modifying operations in  $O(\min\{i, n-i\})$  time, where  $i$  is the insertion/erasure point

### SGI STL implementation

- two levels: index blocks and data blocks; data blocks are of a fixed size; only the two extreme data blocks can be non-full
- unbounded extra space
- $O(1)$  amortized time push operations

## Earlier results

### Vectors and deques [Brodnik et al., 1999]

- sequence operations in  $O(1)$  worst-case time
- $O(\sqrt{n})$  extra space (measured in elements and in objects of the built-in types)
- $\Omega(\sqrt{n})$  is a lower bound for the amount of extra space needed

### Vectors [Goodrich and Kloss II, 1999]

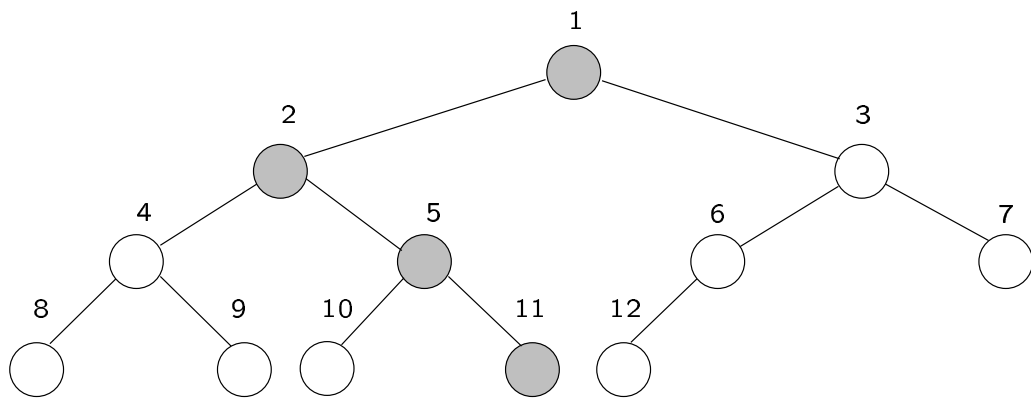
- modifying operations in  $O(n^\varepsilon)$  amortized time for any fixed constant  $\varepsilon > 0$

### Deque [Mortensen, 2001]

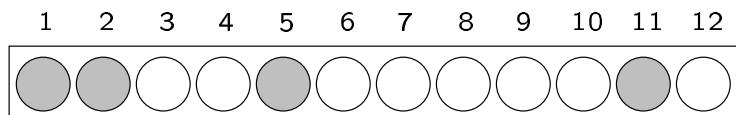
- some implementation details were missing in [Brodnik et al., 1999]
- after filling in these details the implementation got complicated

# Piles (and heaps)

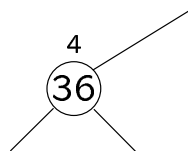
Shape property:



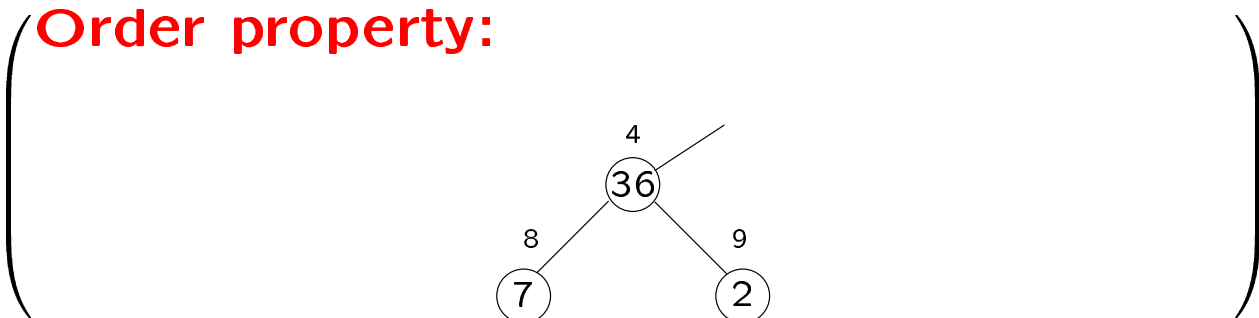
Representation property:



Capacity property:

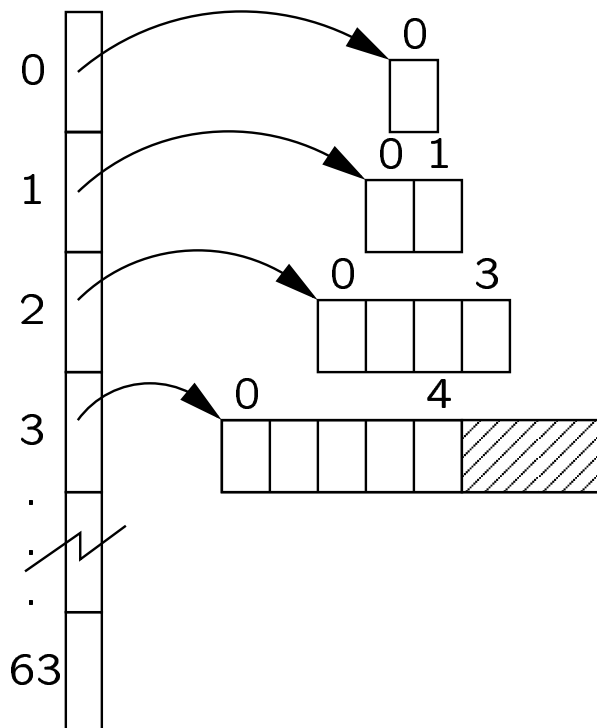


Order property:



# Levelwise-allocated piles

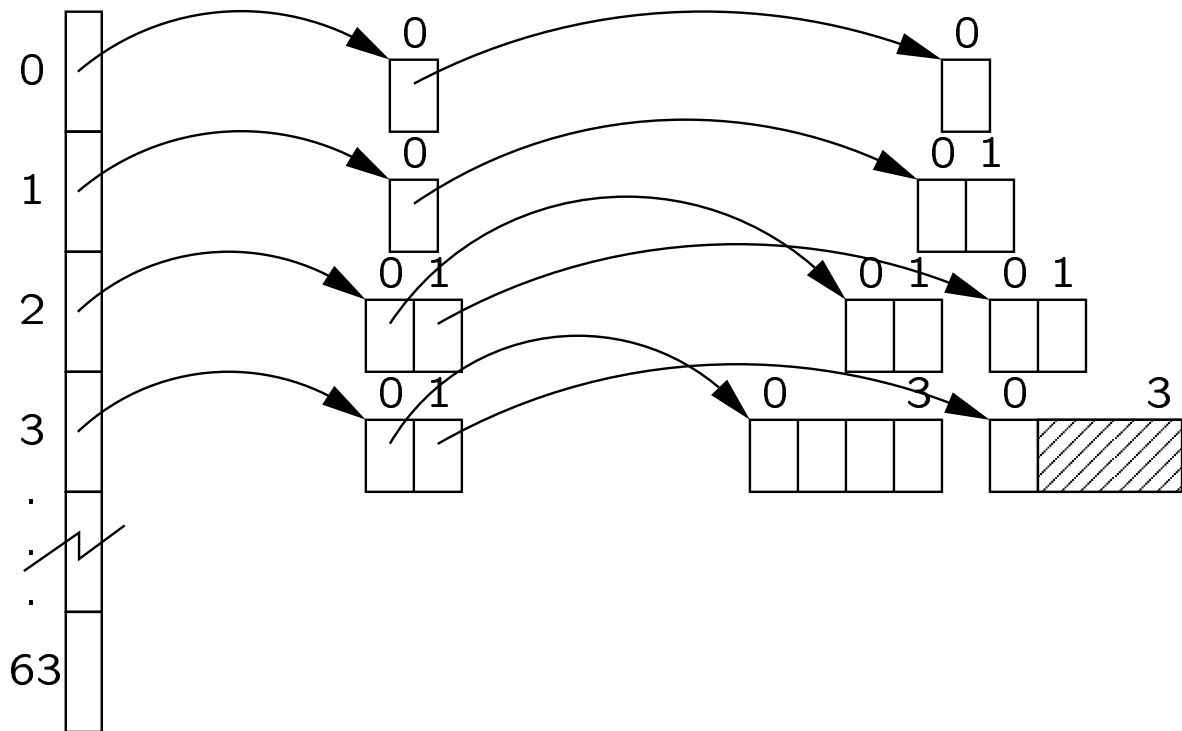
header    levelwise-allocated pile



- sequence operations in  $O(1)$  worst-case time
- element with index  $k \in [0 .. n-1]$  has index  $k - 2^{\lfloor \log_2(k+1) \rfloor} + 1$  at level  $\lfloor \log_2(k+1) \rfloor$
- $O(n)$  extra space
- elements are never moved by `push_back` or `pop_back`

## Blockwise-allocated piles

header    levelwise-allocated twin-pile    blockwise-allocated pile



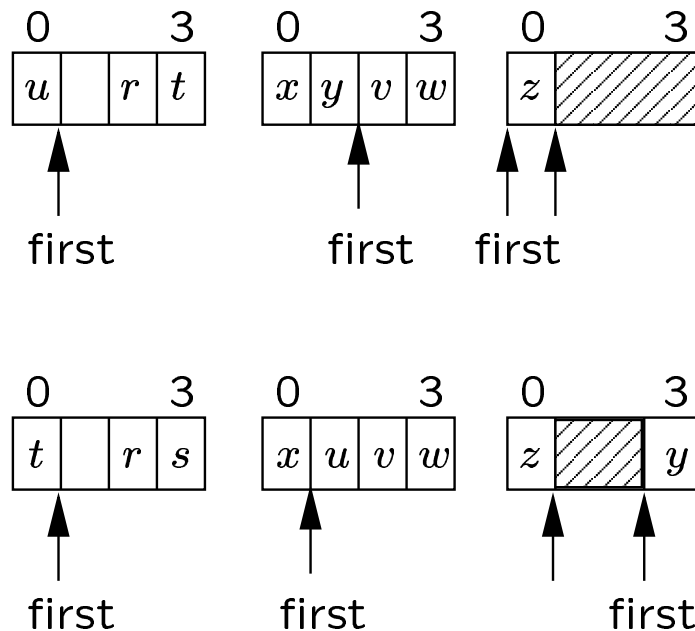
- sequence operations in  $O(1)$  worst-case time
- $O(\sqrt{n})$  extra space
- elements are never moved by `push_back` or `pop_back`



# Faster modifying operations

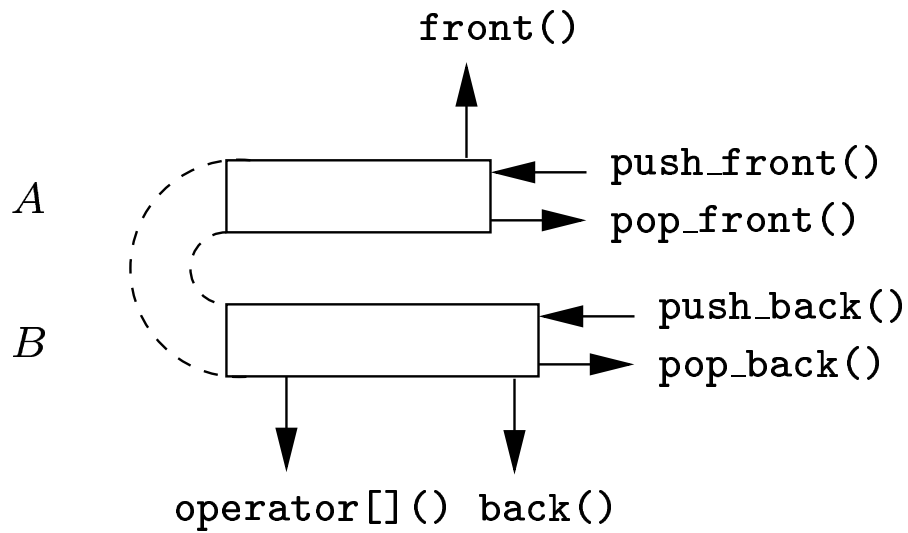
[Goodrich and Kloss II, 1999]

insert element  $s$  between  $r$  and  $t$



- modifying operations in  $O(\sqrt{n})$  worst-case time
- in the twin-pile we have to store double as many pointers

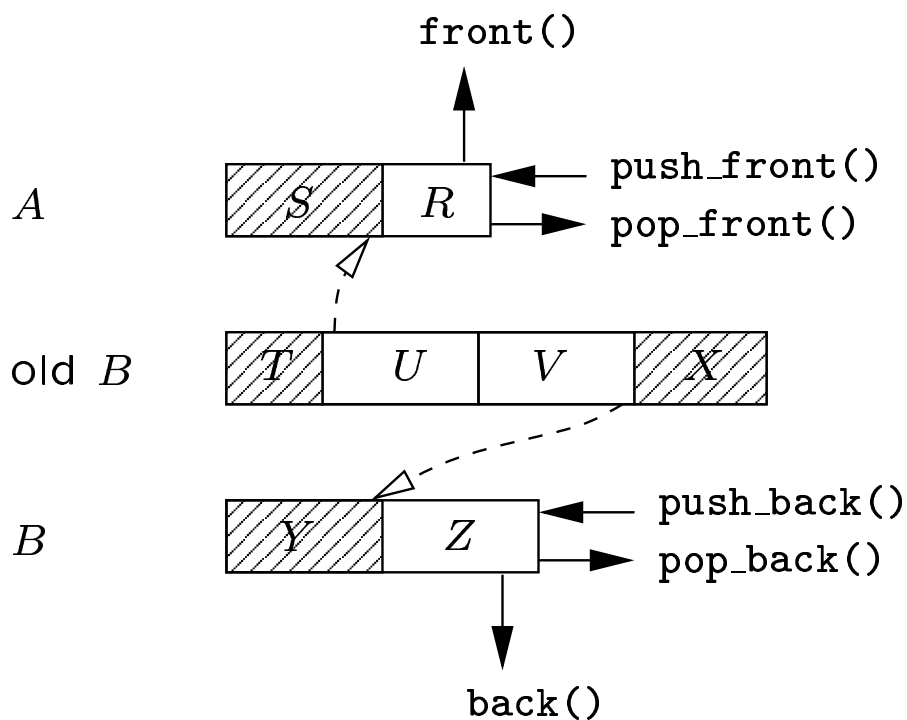
## Space-efficient deques



Everything is easy until *A* or *B* gets empty.

## What if $A$ gets empty?

**Observation:** A space-efficient vector can be constructed backwards, this can be done piecewise, and the structure can be used simultaneously during such a construction.



- sequence operations in  $O(1)$  worst-case time
- modifying operations in  $O(\sqrt{n})$  time
- $O(\sqrt{n})$  extra space

## Some experimental results

<b>container</b>	<b>push_back (ns)</b>	<b>pop_back (ns)</b>
std::deque	85	11
std::vector	115	2
our deque	113	35
our deque (with reorganization)	113	375

<b>container</b>	<b>sequential access (ns)</b>	<b>random access (ns)</b>
std::deque	117	210
std::vector	2	60
our deque	56	160
our deque (with reorganization)	58	162

<b>container</b>	<b>1 000 inserts (s) initial size 10 000</b>	<b>1 000 inserts (s) initial size 100 000</b>	<b>1 000 inserts (s) initial size 1 000 000</b>
std::deque	0.07	1.00	17.5
std::vector	0.015	0.61	12.9
our deque	0.003	0.01	0.04

## Future plans

```
template <
    typename element,
    typename allocator = std::allocator<element>,
    typename implementation =
        bounds_checked_vector<element, allocator>
>
class cphstl::vector {
    ...
}
```

### Possible `std::vector` implementations

- `bounds_checked_vector`
- `contiguous_vector`
- `iterator_safe_vector`
- `space_efficient_vector`

### Possible `std::deque` implementations

- `bounds_checked_deque`
- `two_level_deque`
- `space_efficient_deque`